

# SETUP GUIDE



## Vi-PEC i44 & i88 ECUs to CD-7 Displays

### Supported Devices

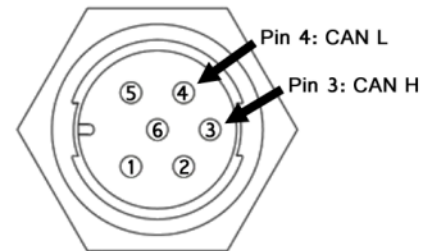
Vi-PEC i44 ECU  
Vi-PEC i88 ECU

### CAN Bus Wiring

AEM CD has 2 separate CAN ports. For 3rd party devices, AEM recommends you use AEM CAN Bus 2, whose connections are contained in a 2 pin Deutsch DTM connector. On older harnesses it may be in an unterminated, twisted/shielded flying lead in the dash harness.

The i44 & i88 have a dedicated communication port which contains the CAN Hi and CAN Lo connections. The simplest method of connecting the CD-7 to these ECU's is to use the AEM to Link/ViPEC adapter harness (AEM P/N 30-2215). Doing this enables the CD-7 to be driven directly off the Communication connector and is a simple plug & play installation. Please take care if you are not using the AEM PnP Adaptor and are using the ViPEC flying lead cable (P/N CANDASH) that ViPEC states should not be used for CAN only comms as it has the RS232 wires in it as well, and will corrupt your USB communications. We can confirm that using the CANDASH lead, even with the RS232 wires unterminated and insulated prevents the USB comms from working properly.

Vi-PEC CAN HIGH (Pin 3) → AEM CD Dash "CAN 2" 2 Pin DTM Pin 1 (CAN 2+), Gray wire in twisted/shielded pair  
Vi-PEC CAN LOW (Pin 4) → AEM CD Dash "CAN 2" 2 Pin DTM Pin 2 (CAN 2-), Black wire in twisted/shielded pair



#### Terminating Resistors:

The Vi-PEC i44 & i88 ECU's have terminating resistors installed internally. As long as the ECU is on one physical end of the CAN Network and the CD-7 is on the other with its terminating resistor activated then no further action regarding terminating resistors is required.

### ECU Software Setup

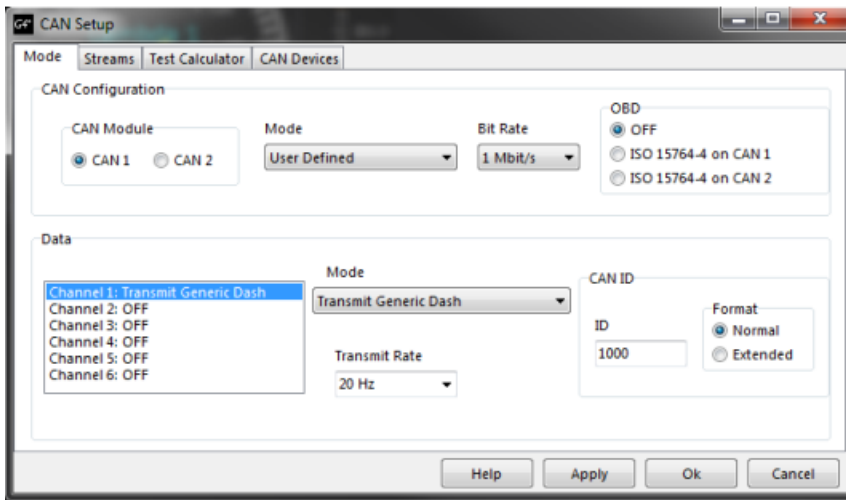
The 'Transmit Generic Dash' mode sends out a range of common parameters and is designed for dashes that are able to have a custom configuration.

1. Open the CAN Setup window (PCLink > ECU Controls > CAN Setup)
2. Select the CAN module to be used
3. Set the Mode to 'User Defined'.
4. Configure the Bit Rate to 1 Mbit/s
5. Select a spare CAN channel.
6. Select 'Transmit Generic Dash' from the Mode drop-down menu.
7. Set the CAN ID to 1000.
8. Set the Format to "Normal"
9. Set the Transmit Rate to 20Hz
10. Click Apply, then OK
11. Make sure a Store (F4) is performed.

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It should look something like this when you are done;



## Supported Channels

The CD Dash supports the following 54 data channels transmitted by the i44 and i88 ECUs:

CH	Channel Name
1	EngineSpeed
2	IntakeManifoldAirPress
3	BoostPress
4	BaroPress
5	ThrottlePos
6	FuelInjDutyPrimary
7	FuelInjDutySecondary
8	FuelInjPulsewidth
9	CoolantTemp
10	IntakeManifoldAirTemp
11	MassAirflow
12	GearPosCalculated
13	FuelInjTiming
14	IgnitionTiming
15	CamIntakeLBankPos

CH	Channel Name
19	AFR1
20	AFR2
21	FuelPress
22	OilTemp
23	OilPress
24	ECUBatteryVoltage
25	WheelSpeedFrontLeft
26	WheelSpeedRearLeft
27	WheelSpeedFrontRight
28	WheelSpeedRearRight
29	KnockLevelCyl1
30	KnockLevelCyl2
31	KnockLevelCyl3
32	KnockLevelCyl4
33	KnockLevelCyl5

CH	Channel Name
37	ECU_FaultCodes
38	ECU_TriggerCounter
39	RPM_Limit
40	MAP_Limit
41	Speed_Limit
42	MaxIgnition_Flag
43	Antilag_Ign_Cut
44	HighSupplyVoltage_Limit
45	Overrun_Flag
46	Traction_Limit
47	LowSupplyVoltage_Flag
48	LaunchRPM_Limit
49	Wakeup_Flag
50	GP_RPM_Limit1
51	CL_Stepper_Limit

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CH	Channel Name
16	CamIntakeRBankPos
17	CamExhaustLBankPos
18	CamExhaustRBankPos

CH	Channel Name
34	KnockLevelCyl6
35	KnockLevelCyl7
36	KnockLevelCyl8

CH	Channel Name
52	GP_RPM_Limit2
53	Ethrottle_Limit
54	Cyclic_Idle_Active

The CD-7 also supports the following 109 ECU Fault Codes transmitted by the i44, i88 & G4+ ECUs:

Accel Pos (Main) High Volt Error  
 Accel Pos (Main) Low Volt Error  
 Accel Pos (Sub) High Volt Error  
 Accel Pos (Sub) Low Volt Error  
 Accel Pos Track Error  
 IAT Error High Volt  
 IAT Error Low Volt  
 IAT Signal Error  
 MAP Error High Volt  
 MAP Error Low Volt  
 MAP Limit  
 MAP Signal Error  
 ECT Error High Volt  
 ECT Error Low Volt  
 ECT Signal Error  
 TPS Error High Volt  
 TPS Error Low Volt  
 TPS Signal Error  
 TP (Main) not selected  
 TP (Sub) not selected  
 TP Tracking Error  
 TP 2 Tracking Error  
 TP 2 (Main) Fault  
 TP 2 (Sub) Fault  
 TPS (Main) Error High Volt  
 TPS (Main) Error Low Volt  
 TPS (Sub) Error High Volt  
 TPS (Sub) Error Low Volt  
 AP (Main) not selected  
 AP (Sub) not selected  
 APS CAN Signal Lost  
 GDI Pump Ctrl High Press Fault  
 GDI Pump Ctrl Low Press Fault  
 RPM Limit  
 Analog 5V Supply Error  
 Aux 17-20 Supply Error  
 Aux 9/10 Volt Supply Error

An V1 Error High Volt  
 An V1 Error Low Volt  
 An V1 Signal Error  
 An V2 Error High Volt  
 An V2 Error Low Volt  
 An V2 Signal Error  
 An V3 Error High Volt  
 An V3 Error Low Volt  
 An V3 Signal Error  
 An V4 Error High Volt  
 An V4 Error Low Volt  
 An V4 Signal Error  
 An V5 Error High Volt  
 An V5 Error Low Volt  
 An V5 Signal Error  
 An V6 Error High Volt  
 An V6 Error Low Volt  
 An V6 Signal Error  
 An V7 Error High Volt  
 An V7 Error Low Volt  
 An V7 Signal Error  
 An V8 Error High Volt  
 An V8 Error Low Volt  
 An V8 Signal Error  
 An V9 Error High Volt  
 An V9 Error Low Volt  
 An V9 Signal Error  
 An V10 Error High Volt  
 An V10 Error Low Volt  
 An V10 Signal Error  
 An V11 Error High Volt  
 An V11 Error Low Volt  
 An V11 Signal Error  
 An V12 Error High Volt  
 An V12 Error Low Volt  
 An V12 Signal Error

An V13 Error High Volt  
 An V13 Error Low Volt  
 An V13 Signal Error  
 An V14 Error High Volt  
 An V14 Error Low Volt  
 An V14 Signal Error  
 An V15 Error High Volt  
 An V15 Error Low Volt  
 An V15 Signal Error  
 An V16 Error High Volt  
 An V16 Error Low Volt  
 An V16 Signal Error  
 An T1 Error High Volt  
 An T1 Error Low Volt  
 An T1 Signal Error  
 An T2 Error High Volt  
 An T2 Error Low Volt  
 An T2 Signal Error  
 An T3 Error High Volt  
 An T3 Error Low Volt  
 An T3 Signal Error  
 An T4 Error High Volt  
 An T4 Error Low Volt  
 An T4 Signal Error  
 E-Throttle1 Low Ctrl Volt Error  
 E-Throttle1 Low Volt Error  
 E-Throttle1 Max Duty Error  
 E-Throttle1 Min Duty Error  
 E-Throttle1 Curr/Temp Error  
 E-Throttle1 Pos Ctrl Error  
 E-Throttle2 Low Ctrl Volt Error  
 E-Throttle2 Low Volt Error  
 E-Throttle2 Max Duty Error  
 E-Throttle2 Min Duty Error  
 E-Throttle2 Curr/Temp Error  
 E-Throttle2 Pos Ctrl Error

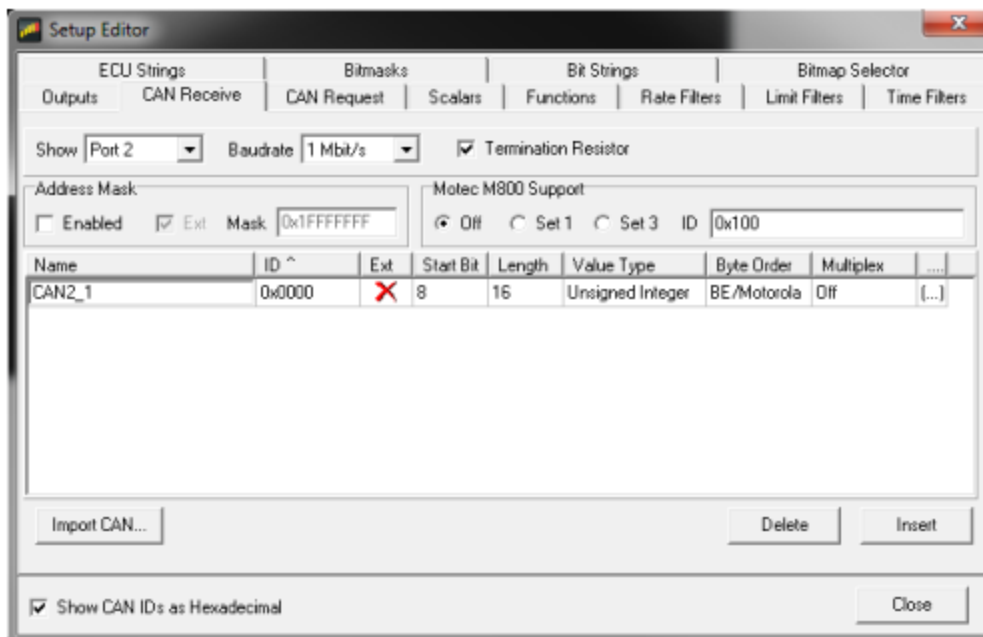
## Layout Overview & CAN Setup

The fastest way to get something working is to use the AEM created setup for the Vi-PEC/G4+ ECU.

It is titled “Default-Black-LinkG4+.aemcd7” and can be found in the same location as this document was. This is a version of our default black layout that has the Vi-PEC CAN inputs pre-configured and includes the 54 data channels listed earlier as well the 109 distinct ECU fault codes. If you choose this method then simply load this configuration into the dash and as long as the CAN is connected to CAN2 then you are done.

If you want to create something from scratch, you can either start with a new dash layout by selecting “File” then “New” in DashDesign or you can select from a pre-designed layout that has screens already designed and inserted but has the CAN inputs left blank. These are chosen by selecting “File” then “Open” and selecting one of the setups titled xzyblank.aemcd7 with the xyz representing a description of the layouts contained in the file.

To import the CAN configuration into your setup you select “Setup” then “Display” from the main DashDesign menu. Once the dialog box opens you select the “CAN Receive” tab.



Change the settings to the following:

**Show:** “Port 2”

**Baudrate:** 1 Mbit/s

**Termination Resistor:** “ON”

**Address Mask:** “OFF”

**M800 Support:** “OFF”

Then click on “Import CAN” on the lower left and select the Vi-PEC/Link G4+ CAN setup file. The new items will appear in the Outputs tab. They can now be viewed on the display or logged. You can rename, filter, or manipulate any of these channels to make them more useful. There will also be a Variable String (dynamic text) channel created called “ECU\_FaultCodes\_string” which can be used to display a scrolling list of the current ECU Fault Codes.